Fuzzy Stochastic Differential Equations: A Tool for Stochastic Systems with Imprecise Values

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 (Ω, \mathcal{A}, P) - a complete probability space. $\{\mathcal{A}_t\}_{t\in [0,T]}$ - a filtration satisfying usual hypotheses.

$$
dx(t) = f(t, x(t))dt + g(t, x(t))dB(t), \quad x(0) = x_0
$$

$$
x(t) = x_0 + \int_0^t f(s, x(s))ds + \int_0^t g(s, x(s))dB(s), \quad t \in [0, T],
$$

$$
f, g \colon [0, T] \times \mathbf{R}^d \to \mathbf{R}^d,
$$

$$
x_0 \text{ is an } \mathcal{A}_0\text{-measurable random variable,}
$$

$$
\{B(t), t \in [0, T]\} \text{- Brownian motion.}
$$

Solution: a stochastic process $x\colon [0,T]\times\Omega\to \mathbf{R}^d.$

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Applications: biology, financial mathematics, control theory, physics, economics, mechanical and electrical engineering.

Monographs (among others):

- 1. L. Arnold, Stochastic Differential Equations: Theory and Applications, John Willey & Sons, New York 1974.
- 2. I.I. Gihman, A.V. Skorohod, Stochastic Differential Equations, Springer, Berlin 1972.
- 3. N. Ikeda, S. Watanabe, Stochastic Differential Equations and Diffusion Processes, Kodansha, Tokyo 1981.
- 4. H. Kunita, Stochastic Flows and Stochastic Differential Equations, Cambridge Univ. Press, Cambridge 1990.
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Lotfi A. Zadeh 1965:

A **fuzzy set** (class) u in \mathbf{R}^d is characterized by a membership function $u\colon \mathbf{R}^d \to [0,1]$ which associates with each point in \mathbf{R}^d a real number in the interval $[0, 1]$.

The value $u(x)$ represents the grade of membership of x in u .

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Example: the class "Hot water"

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Fuzzy sets

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Notation

$$
\mathcal{F}(\mathbf{R}^d) \ := \ \begin{cases} u : \mathbf{R}^d \to [0,1] \mid [u]_{\alpha} \text{ is a nonempty, convex} \\ \text{and compact subset of } \mathbf{R}^d \text{ for } \alpha \in [0,1] \end{cases}
$$

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Two sources of uncertainties

Fuzzy Stochastic Differential Equations (FSDEs)

 $dx(t) = f(t, x(t))dt + q(t, x(t))dB(t), \quad x(0) = x_0$

 $f,g\colon [0,T]\times \mathcal{F}(\mathbf{R}^d)\to \mathcal{F}(\mathbf{R}^d)$ - fuzzy coefficients, $x_0\colon \Omega\to \mathcal{F}(\mathbf{R}^d)$ is an \mathcal{A}_0 -measurable fuzzy random variable, ${B(t), t \in [0, T]}$ - real-valued Brownian motion.

Solution: a fuzzy stochastic process $x\colon [0,T]\times \Omega\to \mathcal{F}(\mathbf{R}^d).$

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 $\mathbf{A} \equiv \mathbf{A} + \mathbf{A} \mathbf{B} + \mathbf{A} \mathbf{B} + \mathbf{A} \mathbf{B} + \mathbf{A} \mathbf{B}$

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Integral form of FSDEs

$$
x(t) = x_0 + \int_0^t f(s, x(s))ds + \int_0^t g(s, x(s))dB(s), \quad t \in [0, T],
$$

- addition of fuzzy sets,
- fuzzy stochastic Lebesgue integral,
- fuzzy stochastic Itô integral.

Addition of fuzzy sets $u,v\in \mathcal{F}(\mathbf{R}^d)$:

 $u+v$ is a fuzzy set in $\mathcal{F}(\mathbf{R}^d)$ such that for every $\alpha \in [0,1]$

 $[u + v]_{\alpha} = [u]_{\alpha} + [v]_{\alpha} \leftarrow$ Minkowski's sum of sets.

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Fuzzy stochastic integrals

 $a \colon [0,T] \times \Omega \to \mathcal{F}(\mathbf{R}^d)$ - measurable, adapted and integrally bounded fuzzy stochastic process

$$
\int_0^t a(s,\omega)ds
$$
 - fuzzy stochastic Lebesgue integral,

$$
\left[\int_0^t a(s,\omega)ds\right]_\alpha = \int_0^t [a(s,\omega)]_\alpha ds \leftarrow \text{Aumann's integral.}
$$

Theorem 1 (MTM 2009, 2012).

The mapping $[0,T]\times \Omega \ni (t,\omega) \mapsto \int_0^t a(s,\omega)ds \in \mathcal{F}(\mathbf{R}^d)$ is a measurable, adapted and integrally bounded fuzzy stochastic process. Its trajectories are continuous.

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 b - fuzzy stochastic process,

 B - real-valued Brownian motion.

$$
\int_0^t b(s)dB(s)
$$
 - fuzzy stochastic Itô integral.

Theorem 2 (Ogura & Zhang 2010).

It is not possible to define a fuzzy stochastic Itô integral $\Big({\textstyle\int_0^t} b(s) dB(s)\Big)(\omega)$ in such a way that it is a fuzzy (and non-crisp) stochastic process.

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$$
x(t) = \underbrace{x_0}_{\text{fuzzy-valued}} + \underbrace{\int_0^t f(s, x(s)) ds}_{\text{fuzzy-valued}} + \underbrace{\int_0^t g(s, x(s)) dB(s)}_{\text{crisp}},
$$

 $f \colon [0,T] \times \Omega \times \mathcal{F}(\mathbf{R}^d) \to \mathcal{F}(\mathbf{R}^d)$, $g\colon [0,T]\times\Omega\times\mathcal{F}(\mathbf{R}^d)\to\mathbf{R}^d$, $x_0\colon \Omega\to \mathcal{F}(\mathbf{R}^d)$ is a fuzzy random variable, B- real-valued Brownian motion.

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$$
dx(t) = f(t, x(t))dt + \langle g(t, x(t))dB(t) \rangle, \quad x(0) = x_0 \tag{1}
$$

$$
x(t) = x_0 + \int_0^t f(s, x(s))ds + \langle \int_0^t g(s, x(s))dB(s) \rangle, \quad t \in [0, T],
$$

Definition 3.

By a **solution to Eq.** (1) we mean a measurable, adapted and integrally bounded fuzzy stochastic process $x\colon [0,T]\times \Omega\to \mathcal{F}(\mathbf{R}^d)$ with continuous trajectories and such that P -a.e.

$$
x(t) = x_0 + \int_0^t f(s, x(s))ds + \left\langle \int_0^t g(s, x(s))dB(s) \right\rangle, \quad t \in [0, T].
$$

The **solution** x is unique if P-a.e. $x(t) = y(t)$, $t \in [0, T]$, where $y \colon [0,T] \times \Omega \to \mathcal{F}(\mathbf{R}^d)$ is any other solutio[n t](#page-11-0)[o E](#page-13-0)[q.](#page-12-0) $(1).$ $(1).$

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Example: $x(t) = x_0 + \int_0^t 2sx(s)ds + \left\langle \int_0^t 4dB(s) \right\rangle$. Solution: $x(t) = e^{t^2} \cdot x_0 + \left\langle 4e^{t^2} \int_0^t e^{-s^2} dB(s) \right\rangle$. For a simulation: $[x_0(\omega)]_0 = [10, 20]$, $[x(t, \omega)]_0 = [L_0(t, \omega), U_0(t, \omega)]$.

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Notation

$$
\text{Fuzz}(u) := \text{diam}([u]_0) \text{ for } u \in \mathcal{F}(\mathbf{R}^d).
$$

Proposition 4 (MTM 2013).

Assume that $x\colon [0,T]\times \Omega\to \mathcal{F}(\mathbf{R}^d)$ is a solution to Eq. (1). Then P-a.a. the functions $t \mapsto \text{Fuzz}(x(t, \omega))$ are nondecreasing.

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Example: $x(t) + \int_0^t (-2)sx(s)ds + \left\langle \int_0^t (-4)dB(s) \right\rangle = x_0.$ Solution: $x(t) = \left[\cosh(t^2) \cdot x_0 \ominus \left(-\sinh(t^2) \cdot x_0\right)\right] + \left\langle 4e^{t^2} \int_0^t e^{-s^2} dB(s) \right\rangle.$ For a simulation: $[x_0(\omega)]_0 = [50, 150]$, $[x(\bar{t}, \omega)]_0 = [L_0(t, \omega), U_0(t, \omega)]$.

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Consider

$$
x(t) + \int_0^t (-1)f(s, x(s))ds + \left\langle \int_0^t (-1)g(s, x(s))dB(s) \right\rangle = x_0.
$$
 (2)

Proposition 5 (MTM 2014).

Assume that $x: [0, T] \times \Omega \rightarrow \mathcal{F}(\mathbf{R}^d)$ is a solution to Eq. (2). Then P-a.a. the functions $t \mapsto \text{Fuzz}(x(t, \omega))$ are nonincreasing.

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Bipartite fuzzy stochastic differential equations

$$
x(t) + \int_0^t (-1)f_1(s, x(s))ds + \left\langle \int_0^t (-1)g_1(s, x(s))dB_1(s) \right\rangle
$$

= $x_0 + \int_0^t f_2(s, x(s))ds + \left\langle \int_0^t g_2(s, x(s))dB_2(s) \right\rangle.$

$$
x(t) + \int_0^t (-1)f_1(s, x(s))ds
$$

= $x_0 + \int_0^t f_2(s, x(s))ds + \left\langle \int_0^t g(s, x(s))dB(s) \right\rangle.$ (3)

 $g = (g_1, g_2)$ $B = (B_1, B_2)'$.

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Assumptions:

(a1) $f_k(\cdot, \cdot, \cdot)$: $[0, T] \times \Omega \times \mathcal{F}(\mathbf{R}^d) \to \mathcal{F}(\mathbf{R}^d)$, $k = 1, 2$, $g(\cdot,\cdot,\cdot)\colon [0,T]\times \Omega\times \mathcal{F}(\mathbf{R}^d)\to \mathbf{R}^d$ are jointly measurable mappings,

(a2) there exists a constant $L > 0$ such that $\forall (t, \omega) \in [0, T] \times \Omega \quad \forall u, v \in \mathcal{F}(\mathbf{R}^d)$

 $\max\{D(f_k(t,\omega,u),f_k(t,\omega,v)),||g(t,\omega,u)-g(t,\omega,v)||\}\leq L D(u,v),$

(a3) there exists a constant $C > 0$ such that $\forall (t, \omega) \in [0, T] \times \Omega$

 $\max \{D(f_k(t, \omega, \langle 0 \rangle), \langle 0 \rangle), ||g(t, \omega, \langle 0 \rangle)||\} \leq C.$

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Theorem 6 (MTM 2016).

Let assumptions (a1)-(a3) be satisfied. Suppose that the sequence $\{x_n\}_{n=0}^\infty$ of the fuzzy stochastic processes $x_n\colon [0,\tilde{T}]\times \Omega\to \mathcal{F}(\mathbb{R}),$ where $T \leq T$, described as: $x_0(t) = x_0$ and for $n = 1, 2, \ldots$

$$
x_n(t) = \left(\left[x_0 + \int_0^t f_2(s, x_{n-1}(s)) ds \right] \ominus \int_0^t (-1) f_1(s, x_{n-1}(s)) ds \right) + \left\langle \int_0^t g(s, x_{n-1}(s)) dB(s) \right\rangle
$$

is well defined. Then Eq. (3) possesses a unique local solution.

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Assumptions:

(b1) $f_k(\cdot, \cdot, \cdot): [0, T] \times \Omega \times \mathcal{F}_c(\mathbf{R}^d) \to \mathcal{F}_c(\mathbf{R}^d)$, $k = 1, 2$, $g(\cdot,\cdot,\cdot)\colon [0,T]\times \Omega\times \mathcal F_c(\mathbf{R}^d)\to \mathbf{R}^d$ are jointly measurable mappings,

(b2)
$$
\forall (t, \omega) \in [0, T] \times \Omega
$$
 $\forall u, v \in \mathcal{F}_c(\mathbf{R}^d)$

 $\max\{D^2(f_k(t,\omega,u),f_k(t,\omega,v)),\|g(t,\omega,u)-g(t,\omega,v)\|^2\} \leq \xi(D^2(u,v)),$

where $\xi: \mathbf{R}_{+} \to \mathbf{R}_{+}$ is continuous, concave, nondecreasing, $\xi(0)=0$, $\xi(a)>0$ for $a>0$, and \int_{0+} $\frac{da}{\xi(a)}=\infty$, (b3) there exists a constant $C > 0$ such that $\forall (t, \omega) \in [0, T] \times \Omega$

$$
\max \left\{ D^2(f_k(t,\omega,\langle 0 \rangle),\langle 0 \rangle),\|g(t,\omega,\langle 0 \rangle)\|^2 \right\} \leqslant C.
$$

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Theorem 7 (MTM 2017).

Let assumptions (b1)-(b3) be satisfied. Suppose that there exists $\tilde{T} \in (0, T]$ such that

$$
\int_{\tau}^{t}f_2(s,x(s))ds \ominus \int_{\tau}^{t}f_1(s,x(s))ds
$$

is well defined for all $\tau, t \in [0, \tilde{T}]$ and for every fuzzy stochastic process x . Then Eq. (3) possesses a unique local solution.

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Thank you for your attention!

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