

Positive radial solutions for systems involving potential Lane-Emden nonlinearities and Minkowski operator

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Introduction

Let Ω be a bounded domain in \mathbb{R}^N ($N \geq 2$) with boundary $\partial\Omega$ of class C^2 .

$$\begin{cases} \mathcal{M}(u) + \lambda F_u(x, u, v) = 0, & x \in \Omega, \\ \mathcal{M}(v) + \lambda F_v(x, u, v) = 0, & x \in \Omega, \\ u|_{\partial\Omega} = 0 = v|_{\partial\Omega}, \end{cases} \quad (1)$$

with $F : \Omega \times \mathbb{R}^2 \rightarrow \mathbb{R}$ satisfying:

- (H_F) (i) $F(\cdot, u, v) : \Omega \rightarrow \mathbb{R}$ is measurable for all $(u, v) \in \mathbb{R}^2$ and $F(\cdot, 0, 0) = 0$;
 (ii) $F(x, \cdot, \cdot) : \mathbb{R}^2 \rightarrow \mathbb{R}$ is of class C^1 on \mathbb{R}^2 for a.e. $x \in \Omega$;
 (iii) for each $\rho > 0$ there is some $\alpha_\rho \in L^\infty(\Omega)$ such that

$$|\nabla F(x, u, v)| \leq \alpha_\rho(x) \text{ for a.e. } x \in \Omega, \forall (u, v) \in \mathbb{R}^2 \text{ with } |(u, v)| \leq \rho,$$

- By a **solution** of (1) we mean a couple of functions $(u, v) \in W^{2,p}(\Omega) \times W^{2,q}(\Omega)$ with some $p, q > N$, such that $\|\nabla u\|_\infty < 1$, $\|\nabla v\|_\infty < 1$, which satisfies the equations a.e. in Ω and vanishes on $\partial\Omega$.

Theorem 1.

Assume (H_F) and that

$$\begin{aligned} F(x, 0, v) = F_u(x, 0, v) = F_u(x, u, 0) = 0 \quad \text{and} \\ F(x, u, 0) = F_v(x, u, 0) = F_v(x, 0, v) = 0, \end{aligned} \quad (2)$$

for a.e. $x \in \Omega$ and all $(u, v) \in [0, \infty)^2$.

If the following hold true:

$$(iv) \exists R_1 > 0 : \begin{cases} F_u(x, u, v) > (\geq) 0 \\ F_v(x, u, v) \geq (>) 0 \end{cases}, \text{ for a.e. } x \in \Omega, \forall u, v \in (0, R_1);$$

$$(v) \lim_{|(u,v)| \rightarrow 0} \frac{F(x, u, v)}{|(u, v)|^2} = 0 \text{ uniformly with } x \in \Omega,$$

then there exists $\Lambda > 0$ s.t. for all $\lambda > \Lambda$ problem (1) has at least **two** solutions with each component **nontrivial** (and non-negative).

Proof. Set $\tilde{F}(x, u, v) = F(x, u_+, v_+)$ ($x \in \Omega$, $u, v \in \mathbb{R}$) and consider

$$\begin{cases} \mathcal{M}(u) + \lambda \tilde{F}_u(x, u, v) = 0, & x \in \Omega, \\ \mathcal{M}(v) + \lambda \tilde{F}_v(x, u, v) = 0, & x \in \Omega, \\ u|_{\partial\Omega} = 0 = v|_{\partial\Omega} \end{cases} \quad (3)$$

- (u, v) solution for (3) $\Rightarrow (u, v)$ has non-negative components and solves (1).

$$K_0 := \{u \in W^{1,\infty}(\Omega) : \|\nabla u\|_\infty \leq 1, u|_{\partial\Omega} = 0\}$$

$$\Psi(u) = \begin{cases} \int_{\Omega} [1 - \sqrt{1 - |\nabla u|^2}] & \text{for } u \in K_0 \\ +\infty & \text{for } u \in C(\bar{\Omega}) \setminus K_0 \end{cases}$$

* Ψ is convex and lower semicontinuous on $C(\bar{\Omega})$

$$\tilde{\mathcal{F}}(u, v) = \int_{\Omega} \tilde{F}(x, u, v)$$

* $\tilde{\mathcal{F}}$ is of class C^1 on $C(\bar{\Omega}) \times C(\bar{\Omega})$

$$I_\lambda(u, v) := \Psi(u) + \Psi(v) - \lambda \tilde{\mathcal{F}}(u, v), \quad \forall (u, v) \in C(\bar{\Omega}) \times C(\bar{\Omega})$$

- (u, v) critical point of I_λ (in the sense of Szulkin) $\Rightarrow (u, v)$ solution of (3)
- $\exists \Lambda > 0$ s.t. $\forall \lambda > \Lambda$:
 - (a) I_λ has a negative minimum,
 - (b) I_λ has a positive value at a (mountain pass) critical point $\Rightarrow I_\lambda$ has two nontrivial critical points; each such a critical point is a solution of (3) *having each component nontrivial*.

Example 2.

There exists $\Lambda > 0$ s.t., for all $\lambda > \Lambda$, the system

$$\begin{cases} \mathcal{M}(u) + \lambda uv^2 = 0, & x \in \Omega, \\ \mathcal{M}(v) + \lambda u^2 v = 0, & x \in \Omega, \\ u|_{\partial\Omega} = 0 = v|_{\partial\Omega} \end{cases} \quad (4)$$

has at least two solutions with each component nontrivial and non-negative.

- take $F(x, u, v) = u^2 v^2 / 2$

More general: • $F(x, u, v) = \mu(|x|)u^{p+1}v^{q+1}$ under the hypothesis:

(H) *The non-negative exponents p, q satisfy $\max\{p, q\} > 1$ and the function $\mu : [0, R] \rightarrow [0, \infty)$ is continuous and $\mu(r) > 0$ for all $r \in (0, R]$.*

$$\begin{cases} \mathcal{M}(u) + \lambda\mu(|x|)(p+1)u^p v^{q+1} = 0, & x \in \Omega, \\ \mathcal{M}(v) + \lambda\mu(|x|)(q+1)u^{p+1}v^q = 0, & x \in \Omega, \\ u|_{\partial\Omega} = 0 = v|_{\partial\Omega} \end{cases} \quad (5)$$

Theorem 1 $\Rightarrow \exists \Lambda > 0$ s.t. $\forall \lambda > \Lambda$ the system (5) has at least two solutions with each component nontrivial (and non-negative).

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In the case on a single equation in a ball:

$$\mathcal{M}(u) + \lambda \mu(|x|) u^\alpha = 0 \text{ in } \mathcal{B}(R), \quad u|_{\partial \mathcal{B}(R)} = 0 \quad (\alpha > 1)$$

a **sharper result** holds true: there exists $\Lambda > 0$ s.t. it has zero, at least one or at least two positive solutions according to $\lambda \in (0, \Lambda)$, $\lambda = \Lambda$ or $\lambda > \Lambda$.

• • $r := |x|$ and $u(x) = u(r)$, $v(x) = v(r)$, the *Dirichlet* problem (5) in $\Omega = \mathcal{B}(R)$ reduces to the *mixed* boundary value problem:

$$\begin{cases} [r^{N-1} \varphi(u')] + \lambda r^{N-1} \mu(r) (p+1) u^p v^{q+1} = 0, \\ [r^{N-1} \varphi(v')] + \lambda r^{N-1} \mu(r) (q+1) u^{p+1} v^q = 0, \\ u'(0) = u(R) = 0 = v(R) = v'(0), \end{cases} \quad (6)$$

where

$$\varphi(y) = \frac{y}{\sqrt{1-y^2}} \quad (y \in \mathbb{R}, |y| < 1).$$

Lower and upper solutions

Consider the general system:

$$\begin{cases} [r^{N-1}\varphi(u')] + r^{N-1}f_1(r, u, v) = 0, \\ [r^{N-1}\varphi(v')] + r^{N-1}f_2(r, u, v) = 0, \\ u'(0) = u(R) = 0 = v(R) = v'(0), \end{cases} \quad (7)$$

where $f_1, f_2 : [0, R] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ are continuous.

By a *solution* of (7) we mean a couple of functions $(u, v) \in C^1[0, R] \times C^1[0, R]$ with $\|u'\|_\infty < 1$, $\|v'\|_\infty < 1$ and $r \mapsto r^{N-1}\varphi(u'(r))$, $r \mapsto r^{N-1}\varphi(v'(r))$ of class C^1 on $[0, R]$, which satisfies problem (7). Here and below, we denote by $\|\cdot\|_\infty$ the usual sup-norm on $C := C[0, R]$. We say that $u \in C$ is *positive* if $u > 0$ on $[0, R)$. By a *positive solution* of (7) we understand a solution (u, v) with both u and v positive.

A *lower solution* of (7) is a couple of functions $(\alpha_u, \alpha_v) \in C^1 \times C^1$, s.t. $\|\alpha'_u\|_\infty < 1$, $\|\alpha'_v\|_\infty < 1$, the mappings $r \mapsto r^{N-1}\varphi(\alpha'_u(r))$, $r \mapsto r^{N-1}\varphi(\alpha'_v(r))$ are of class C^1 on $[0, R]$ and satisfies

$$\begin{cases} [r^{N-1}\varphi(\alpha'_u)]' + r^{N-1}f_1(r, \alpha_u, \alpha_v) \geq 0, \\ [r^{N-1}\varphi(\alpha'_v)]' + r^{N-1}f_2(r, \alpha_u, \alpha_v) \geq 0, \\ \alpha_u(R) \leq 0, \quad \alpha_v(R) \leq 0. \end{cases}$$

An *upper solution* $(\beta_u, \beta_v) \in C^1 \times C^1$ is defined by reversing the above inequalities.

- $J_1, J_2 \subset \mathbb{R}$. In the terminology of [14], a function $f = f(r, s, t) : [0, R] \times J_1 \times J_2 \rightarrow \mathbb{R}$ is said to be *quasi-monotone nondecreasing* with respect to t (resp. s) if for fixed r, s (resp. r, t) one has

$$f(r, s, t_1) \leq f(r, s, t_2) \text{ as } t_1 \leq t_2 \quad (\text{resp. } f(r, s_1, t) \leq f(r, s_2, t) \text{ as } s_1 \leq s_2).$$

Proposition 2.1.

If (7) has a lower solution (α_u, α_v) and an upper solution (β_u, β_v) s.t. $\alpha_u(r) \leq \beta_u(r)$, $\alpha_v(r) \leq \beta_v(r)$ for all $r \in [0, R]$ and $f_1(r, s, t)$ (resp. $f_2(r, s, t)$) is quasi-monotone nondecreasing with respect to t (resp. s), then (7) has a solution (u, v) s.t. $\alpha_u(r) \leq u(r) \leq \beta_u(r)$ and $\alpha_v(r) \leq v(r) \leq \beta_v(r)$ for all $r \in [0, R]$.

$$C^1 := C^1[0, R] \text{ with } \|u\|_1 = \|u\|_\infty + \|u'\|_\infty$$

$$C^1 \times C^1 \text{ with } \|(u, v)\| = \max\{\|u\|_\infty, \|v\|_\infty\} + \max\{\|u'\|_\infty, \|v'\|_\infty\}$$

$$\mathcal{C}_M^1 = \{(u, v) \in C^1 \times C^1 : u'(0) = u(R) = 0 = v(R) = v'(0)\}$$

N_{f_i} = the Nemytskii operator associated to f_i ($i = 1, 2$), i.e.,

$$N_{f_i} : C \times C \rightarrow C, \quad N_{f_i}(u, v) = f_i(\cdot, u(\cdot), v(\cdot)) \quad (u, v \in C),$$

$$S : C \rightarrow C, \quad Su(r) = \frac{1}{r^{N-1}} \int_0^r t^{N-1} u(t) dt \quad (r \in [0, R]), \quad Su(0) = 0;$$

$$K : C \rightarrow C^1, \quad Ku(r) = \int_r^R u(t) dt \quad (r \in [0, R]).$$

Proposition 2.2.

A couple of functions $(u, v) \in \mathcal{C}_M^1$ is a solution of (7) if and only if it is a fixed point of the compact nonlinear operator

$$\mathcal{N}_f : \mathcal{C}_M^1 \rightarrow \mathcal{C}_M^1, \quad \mathcal{N}_f = (K \circ \varphi^{-1} \circ S \circ N_{f_1}, K \circ \varphi^{-1} \circ S \circ N_{f_2}).$$

In addition, any fixed point (u, v) of \mathcal{N}_f satisfies

$$\|u'\|_\infty < 1, \quad \|v'\|_\infty < 1, \quad \|u\|_\infty < R, \quad \|v\|_\infty < R, \quad (8)$$

and

$$d_{LS}[I - \mathcal{N}_f, B_\rho, 0] = 1 \text{ for all } \rho \geq R + 1.$$

In particular, problem (7) has at least one solution in B_ρ for all $\rho \geq R + 1$.

- When system (7) is potential:

$$\begin{cases} [r^{N-1}\varphi(u')] = r^{N-1}F_u(r, u, v), \\ [r^{N-1}\varphi(v')] = r^{N-1}F_v(r, u, v), \\ u'(0) = u(R) = 0 = v(R) = v'(0), \end{cases} \quad (9)$$

with $F = F(r, u, v) : [0, R] \times \mathbb{R}^2 \rightarrow \mathbb{R}$ continuous, s.t. F_u and F_v exist and are continuous on $[0, R] \times \mathbb{R}^2$, then a variational approach is available:

$$K_0 = \{u \in W^{1,\infty}[0, R] : \|u'\|_\infty \leq 1, u(R) = 0\}.$$

$$\psi(u) = \begin{cases} \int_0^R r^{N-1} [1 - \sqrt{1 - u'^2}] dr & \text{for } u \in K_0 \\ +\infty & \text{for } u \in C \setminus K_0, \end{cases}$$

$$\Psi(u, v) := \psi(u) + \psi(v), \text{ for all } (u, v) \in C \times C.$$

* Ψ is proper, convex and lower semicontinuous.

$$\mathcal{F}(u, v) := \int_0^R r^{N-1} F(r, u, v), \quad (u, v \in C)$$

* \mathcal{F} is of class C^1 on $C \times C$

$$\mathcal{J} := \Psi + \mathcal{F}$$

Proposition 2.3.

If $(u, v) \in C \times C$ is a critical point of \mathcal{J} (in the sense of Szulkin), then it is a solution of system (9). Moreover, system (9) has a solution which is a minimum point of \mathcal{J} on $C \times C$.

Lemma 3.

Assume that (7) has a lower solution (α_u, α_v) and an upper solution (β_u, β_v) s.t. $\alpha_u(r) \leq \beta_u(r)$, $\alpha_v(r) \leq \beta_v(r)$ for all $r \in [0, R]$ and $f_1(r, s, t)$ (resp. $f_2(r, s, t)$) is quasi-monotone nondecreasing with respect to t (resp. s). Let

$$\mathcal{A}_{\alpha, \beta} := \{(u, v) \in \mathcal{C}_M^1 : \alpha_u \leq u \leq \beta_u, \alpha_v \leq v \leq \beta_v\}.$$

Assume also that (7) has an unique solution (u_0, v_0) in $\mathcal{A}_{\alpha, \beta}$ and there exists $\rho_0 > 0$ s.t. $\overline{B}((u_0, v_0), \rho_0) \subset \mathcal{A}_{\alpha, \beta}$. Then

$$d_{LS}[I - \mathcal{N}_f, B((u_0, v_0), \rho), 0] = 1, \quad \text{for all } 0 < \rho \leq \rho_0,$$

where \mathcal{N}_f stands for the fixed point operator associated to (7).

- $g_1, g_2 : [0, R] \times [0, \infty)^2 \rightarrow [0, \infty)$ continuous

$$\begin{cases} [r^{N-1}\varphi(u')] + r^{N-1}g_1(r, u_+, v_+) = 0, \\ [r^{N-1}\varphi(v')] + r^{N-1}g_2(r, u_+, v_+) = 0, \\ u'(0) = u(R) = 0 = v(R) = v'(0), \end{cases} \quad (10)$$

where $\xi_+ := \max\{0, \xi\}$.

Lemma 4.

Assume that g_1, g_2 satisfy hypothesis:

$$(H_g) \text{ (i) } g_1(r, s, t) > 0 < g_2(r, s, t), \forall s, t > 0, \forall r \in (0, R];$$

$$\text{(ii) } g_1(r, \xi, 0) = g_2(r, 0, \xi) = 0, \forall \xi > 0, \forall r \in (0, R].$$

If there is some $M > 0$ s.t. either

$$\lim_{s \rightarrow 0_+} \frac{g_1(r, s, t)}{s} = 0 \text{ uniformly with } r \in [0, R], t \in [0, M] \quad (11)$$

or

$$\lim_{t \rightarrow 0_+} \frac{g_2(r, s, t)}{t} = 0 \text{ uniformly with } r \in [0, R], s \in [0, M], \quad (12)$$

then there exists $\rho_0 > 0$ s.t.

$$d_{LS}[I - \mathcal{N}_g, B_\rho, 0] = 1 \text{ for all } 0 < \rho \leq \rho_0,$$

where \mathcal{N}_g is the fixed point operator associated to problem (10).

Remark 2.1.

Under hypothesis (H_g) in Lemma 4 any nontrivial solution of problem (10) is a positive solution of the system

$$\begin{cases} [r^{N-1}\varphi(u')] + r^{N-1}g_1(r, u, v) = 0, \\ [r^{N-1}\varphi(v')] + r^{N-1}g_2(r, u, v) = 0, \\ u'(0) = u(R) = 0 = v(R) = v'(0). \end{cases} \quad (13)$$

Back to the gradient system (6) under hypothesis (H)

Theorem 5.

Assume (H). Then there exists $\Lambda > 0$ s.t. the system (6) has zero, at least one or at least two positive solutions according to $\lambda \in (0, \Lambda)$, $\lambda = \Lambda$ or $\lambda > \Lambda$.

Proof. We assume that $0 < q \leq p > 1$ and we make use of the equivalent system:

$$\begin{cases} [r^{N-1}\varphi(u')] + \lambda r^{N-1}\mu(r)(p+1)u_+^p v_+^{q+1} = 0, \\ [r^{N-1}\varphi(v')] + \lambda r^{N-1}\mu(r)(q+1)u_+^{p+1} v_+^q = 0, \\ u'(0) = u(R) = 0 = v(R) = v'(0) \end{cases} \quad (14)$$

$$\mathcal{J}_\lambda(u, v) = \frac{2R^N}{N} - \int_0^R r^{N-1} [\sqrt{1-u'^2} + \sqrt{1-v'^2}] dr - \lambda \int_0^R r^{N-1} \mu(r) u_+^{p+1} v_+^{q+1} dr$$

$$u_0(r) = v_0(r) = R - r \Rightarrow \mathcal{J}_\lambda(u_0, v_0) < 0, \text{ for } \lambda > 0 \text{ large enough}$$

$$\Rightarrow \mathcal{S} := \{\lambda > 0 : (6) \text{ has a positive solution}\} \neq \emptyset$$

1. Existence of Λ ; the cases $\lambda \in (0, \Lambda)$ and $\lambda = \Lambda$

$$\bullet \lambda \in \mathcal{S} \Rightarrow \lambda > 2N / [(p+1)R^{p+q+2} \max_{[0,R]} \mu] (> 0)$$

$$(0 <) \Lambda := \inf \mathcal{S} (< +\infty)$$

$$\bullet \Lambda \in \mathcal{S}$$

2. The case $\lambda > \Lambda$.

• $(\Lambda, \infty) \subset \mathcal{S}$: $\lambda_0 \in (\Lambda, \infty) \stackrel{?}{\Rightarrow} \lambda_0 \in \mathcal{S}$

$\gg (u_\Lambda, v_\Lambda)$ a positive solution of (6) with $\lambda = \Lambda \Rightarrow (u_\Lambda, v_\Lambda)$ is a lower solution for (14) with $\lambda = \lambda_0$ \gg an upper solution (u_{H_1}, v_{H_2}) for (14) with $\lambda = \lambda_0$ can

be constructed s.t. $u_\Lambda < u_{H_1}$ $v_\Lambda < v_{H_2}$

\Rightarrow (14) has a positive solution (Proposition 2.1) $\Rightarrow \lambda_0 \in \mathcal{S}$.

- $\lambda_0 \in (\Lambda, \infty) \stackrel{?}{\Rightarrow}$ (14) with $\lambda = \lambda_0$ has a second positive solution.

>> (u_Λ, v_Λ) be the lower solution and (u_{H_1}, v_{H_2}) be the upper solution constructed as above

>> fix (u_0, v_0) a positive solution of (14) with $\lambda = \lambda_0$ s.t.

$$(u_0, v_0) \in \mathcal{A} := \{(u, v) \in \mathcal{C}_M^1 : u_\Lambda \leq u \leq u_{H_1}, v_\Lambda \leq v \leq v_{H_2}\}.$$

$\gg \exists \varepsilon > 0$ s.t. $\overline{B}((u_0, v_0), \varepsilon) \subset \mathcal{A}$

If (14) has a second solution contained in \mathcal{A} , then it is nontrivial and the proof is complete

⊙ If not, Lemma 3 \Rightarrow

$$d_{LS}[I - \mathcal{N}_{\lambda_0}, B((u_0, v_0), \rho), 0] = 1 \text{ for all } 0 < \rho \leq \varepsilon,$$

where \mathcal{N}_{λ_0} is the fixed point operator associated to (14) with $\lambda = \lambda_0$

⊙ $d_{LS}[I - \mathcal{N}_{\lambda_0}, B_\rho, 0] = 1$ for all $\rho \geq R + 1$ (Proposition 2.2)

⊙ $d_{LS}[I - \mathcal{N}_{\lambda_0}, B_\rho, 0] = 1$ for $\rho > 0$ small (Lemma 4)

▷ $\rho_1, \rho_2 > 0$ be small and $\rho_3 \geq R + 1$ s.t.

$$\bar{B}((u_0, v_0), \rho_1) \cap \bar{B}_{\rho_2} = \emptyset \text{ and } \bar{B}((u_0, v_0), \rho_1) \cup \bar{B}_{\rho_2} \subset B_{\rho_3}$$

Additivity-excision property of Leray-Schauder degree \Rightarrow

$$d_{LS}[I - \mathcal{N}_{\lambda_0}, B_{\rho_3} \setminus [\bar{B}((u_0, v_0), \rho_1) \cup \bar{B}_{\rho_2}], 0] = -1.$$

$\Rightarrow \mathcal{N}_{\lambda_0}$ has a fixed point $(u, v) \in B_{\rho_3} \setminus [\bar{B}((u_0, v_0), \rho_1) \cup \bar{B}_{\rho_2}] \Rightarrow (14)$ has a second positive solution.

Corollary 6.

Assume (H). Then there exists $\Lambda > 0$ s.t. the problem

$$\begin{cases} \mathcal{M}(u) + \lambda\mu(|x|)(p+1)u^p v^{q+1} = 0 & \text{in } \mathcal{B}(R), \\ \mathcal{M}(v) + \lambda\mu(|x|)(q+1)u^{p+1}v^q = 0 & \text{in } \mathcal{B}(R), \\ u|_{\partial\mathcal{B}(R)} = 0 = v|_{\partial\mathcal{B}(R)} \end{cases}$$

has zero, at least one or at least two positive solutions according to $\lambda \in (0, \Lambda)$, $\lambda = \Lambda$ or $\lambda > \Lambda$.

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Thank you for your attention!